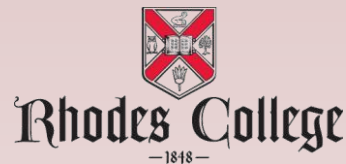


# COMP 355

# Advanced Algorithms

Algorithm Design Review:  
Mathematical Background



# Stable Matching

GALE–SHAPLEY (*preference lists for hospitals and students*)

INITIALIZE  $M$  to empty matching.

WHILE (some hospital  $h$  is unmatched and hasn't proposed to every student)

$s \leftarrow$  first student on  $h$ 's list to whom  $h$  has not yet proposed.

IF ( $s$  is unmatched)

    Add  $h$ – $s$  to matching  $M$ .

ELSE IF ( $s$  prefers  $h$  to current partner  $h'$ )

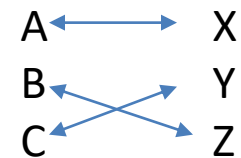
    Replace  $h'$ – $s$  with  $h$ – $s$  in matching  $M$ .

ELSE

$s$  rejects  $h$ .

RETURN stable matching  $M$ .

<u>Hospitals</u>			<u>Students</u>		
<u>Atlanta</u>	<u>Boston</u>	<u>Chicago</u>	<u>Xavier</u>	<u>Yolanda</u>	<u>Zeus</u>
Y	Y	Z	C	C	A
X	Z	Y	B	A	B
Z	X	X	A	B	C



# Polynomial Running Time

- **Brute force.** For many non-trivial problems, there is a natural brute force search algorithm that checks every possible solution.
  - Typically takes  $2^N$  time or worse for inputs of size  $N$ .
  - Unacceptable in practice.
- **Desirable scaling property.** When the input size doubles, the algorithm should only slow down by some constant factor  $c$ .

$n!$  for stable matching with  $n$  hospitals and  $n$  students

There exists constants  $c > 0$  and  $d > 0$  such that on every input of size  $n$ , its running time is bounded by  $c n^d$  steps.

- **Def.** An algorithm is **poly-time** if the above scaling property holds.

# Worst-Case Analysis

- **Worst case running time.** Obtain bound on **largest possible** running time of algorithm on input of a given size  $N$ .
  - Generally captures efficiency in practice.
  - Draconian view, but hard to find effective alternative.
- **Average case running time.** Obtain bound on running time of algorithm on **random** input as a function of input size  $N$ .
  - Hard (or impossible) to accurately model real instances by random distributions.
  - Algorithm tuned for a certain distribution may perform poorly on other inputs.

# Worst-Case Polynomial Time

An algorithm is **efficient** if its running time is polynomial.

**Justification:** It really works in practice!

- Although  $6.02 \times 10^{23} \times N^{20}$  is technically poly-time, it would be useless in practice.
- In practice, the poly-time algorithms that people develop almost always have low constants and low exponents.
- Breaking through the exponential barrier of brute force typically exposes some crucial structure of the problem.

**Exceptions.**

- Some poly-time algorithms do have high constants and/or exponents, and are useless in practice.
- Some exponential-time (or worse) algorithms are widely used because the worst-case instances seem to be rare.

# Big-O Notation

- Asymptotic O-notation (“big-O”) provides a way to simplify the messy functions that often arise in analyzing the running times of algorithms
- Allows us to ignore less important elements (constants)
- Focus on important issues (growth rate for large values of  $n$ )

$$\begin{aligned}f_1(n) &= 43n^2 \log^4 n + \underline{12n^3 \log n} + 52n \log n && \in O(n^3 \log n) \\f_2(n) &= \underline{15n^2} + 7n \log^3 n && \in O(n^2) \\f_3(n) &= 3n + 4 \log_5 n + \underline{91n^2} && \in O(n^2).\end{aligned}$$

# Formal Definition Big-O

- Formally,  $f(n)$  is  $O(g(n))$  if there exist constants  $c > 0$  and  $n_0 \geq 0$  such that,  $f(n) \leq c \cdot g(n)$ , for all  $n \geq n_0$ .
- Thus, big-O notation can be thought of as a way of expressing a sort of fuzzy “ $\leq$ ” relation between functions, where by fuzzy, we mean that constant factors are ignored and we are only interested in what happens as  $n$  tends to infinity.

# Intuitive Form of Big-O

$f(n)$  is  $O(g(n))$  if  $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} \geq c$ , for some constant  $c \geq 0$ .

For example, if  $f(n) = 15n^2 + 7n \log^3 n$  and  $g(n) = n^2$ , we have  $f(n)$  is  $O(g(n))$  because

$$\begin{aligned} \lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} &= \lim_{n \rightarrow \infty} \left( \frac{15n^2 + 7n \log^3 n}{n^2} \right) = \lim_{n \rightarrow \infty} \left( \frac{15n^2}{n^2} + \frac{7n \log^3 n}{n^2} \right) \\ &= \lim_{n \rightarrow \infty} \left( 15 + \frac{7 \log^3 n}{n} \right) = 15. \end{aligned}$$

In the last step of the derivation, we have used the important fact that  $\log n$  raised to any positive power grows asymptotically more slowly than  $n$  raised to any positive power.



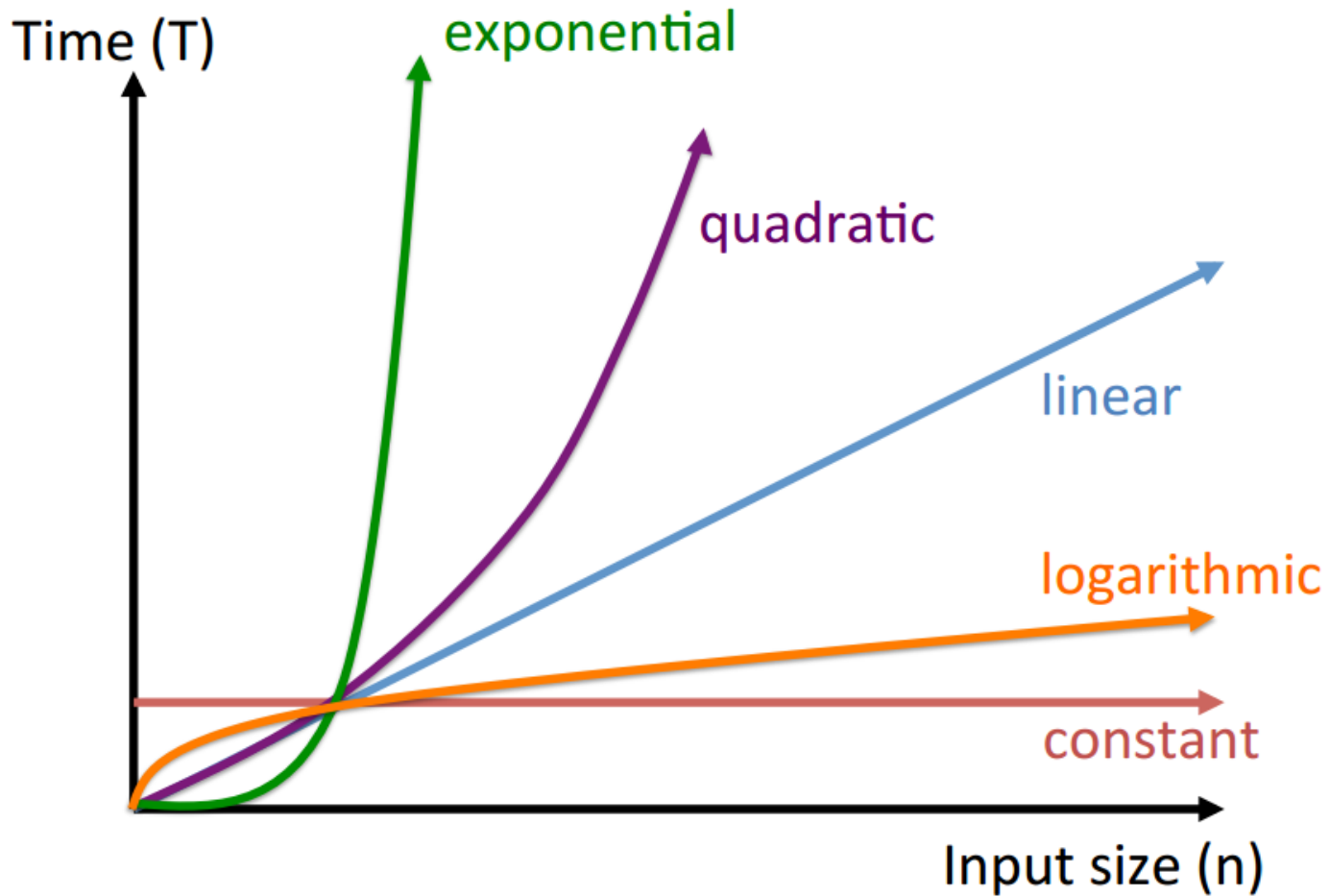
# Useful facts about limits

- For  $a, b > 0$ ,  $\lim_{n \rightarrow \infty} \frac{(\log n)^a}{n^b} = 0$  (polynomials grow faster than polylogs).
- For  $a > 0$  and  $b > 1$ ,  $\lim_{n \rightarrow \infty} \frac{n^a}{b^n} = 0$  (exponentials grow faster than polynomials).
- For  $a, b > 1$ ,  $\lim_{n \rightarrow \infty} \frac{\log_a n}{\log_b n} = c \neq 0$  (logarithm bases do not matter).
- For  $1 < a < b$ ,  $\lim_{n \rightarrow \infty} \frac{a^n}{b^n} = 0$  (exponent bases do matter).

# Survey of Common Running Times

- Linear Time:  $O(n)$
- Linearithmic Time:  $O(n \log n)$
- Quadratic Time:  $O(n^2)$
- Cubic Time:  $O(n^3)$
- Polynomial Time:  $O(n^k)$
- Exponential Time:  $O(2^{n^k})$

# Comparison of Running Times



# Other Asymptotic Forms

- Big-O has a number of relatives, which are useful for expressing other sorts of relations.
- More on these next time!



# Summations

- Naturally arise in analysis of iterative algorithms
- More complex forms of analysis, such as recurrences, are often solved by reducing to summations
- Solving a summation means reducing it to a closed-form formula
  - No summations, recurrences, integrals, or other complex operators
- Often don't need to solve a summation exactly to find the asymptotic approximation

# Summations With General Bounds

**Summations with general bounds:** When a summation does not start at the 1 or 0, as most of the above formulas assume, you can just split it up into the difference of two summations. For example, for  $1 \leq a \leq b$

$$\sum_{i=a}^b f(i) = \sum_{i=0}^b f(i) - \sum_{i=0}^{a-1} f(i).$$

# Linearity of Summation

**Linearity of Summation:** Constant factors and added terms can be split out to make summations simpler.

$$\sum (4 + 3i(i - 2)) = \sum 4 + 3i^2 - 6i = \sum 4 + 3 \sum i^2 - 6 \sum i.$$

Apply the formulas to each summation individually.

# Approximate Using Integrals

**Approximate using integrals:** Integration and summation are closely related. (Integration is in some sense a continuous form of summation.) Here is a handy formula. Let  $f(x)$  be any *monotonically increasing function* (the function increases as  $x$  increases).

$$\int_0^n f(x)dx \leq \sum_{i=1}^n f(i) \leq \int_1^{n+1} f(x)dx.$$



# Example: Previous Larger Element

Given a sequence of numeric values,  $\langle a_1, a_2, \dots, a_n \rangle$ . For each element  $a_i$ , for  $1 \leq i \leq n$ , we want to know the index of the rightmost element of the sequence  $\langle a_1, a_2, \dots, a_{i-1} \rangle$  whose value is strictly larger than  $a_i$ . If no element of this subsequence is larger than  $a_i$  then, by convention, the index will be 0. (Or, if you like, you may imagine that there is a fictitious sentinel value  $a_0 = \infty$ .) More formally, for  $1 \leq i \leq n$ , define  $p_i$  to be  $p_i = \max\{j \mid 0 \leq j < i \text{ and } a_j > a_i\}$ , where  $a_0 = \infty$  (see Fig. 2).

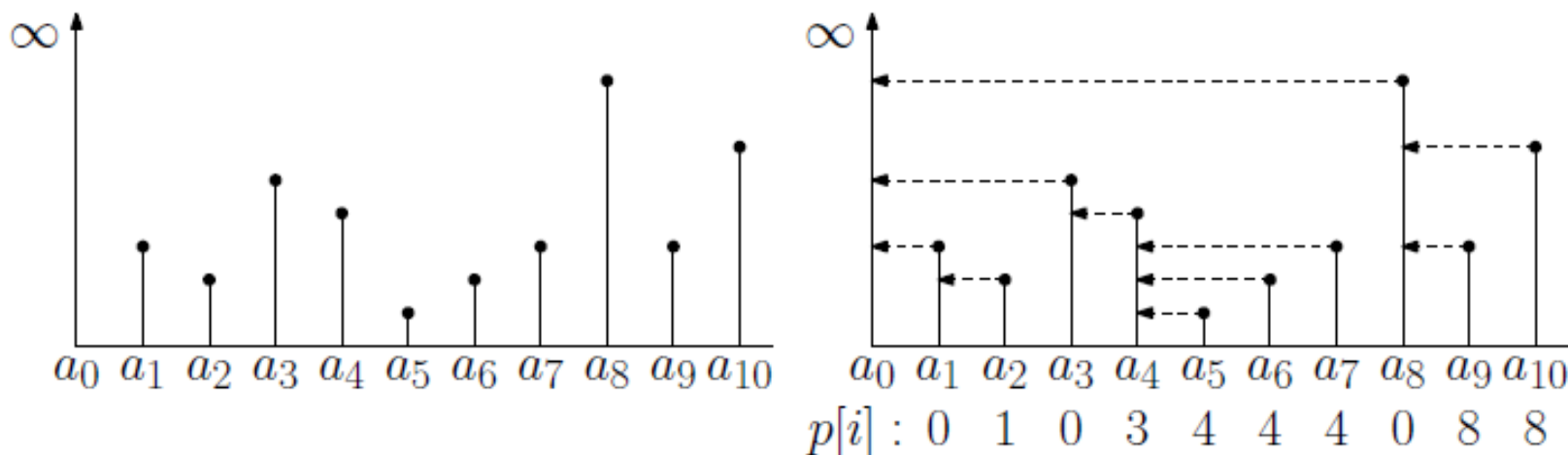


Fig. 2: Example of the previous larger element problem.

# Naive Algorithm For Previous Larger Element

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Previous Larger Element (Naive Solution)

```
// Input: An array of numeric values a[1..n]
// Returns: An array p[1..n] where p[i] contains the index of the previous
// larger element to a[i], or 0 if no such element exists.
previousLarger(a[1..n]) {
    for (i = 1 to n)
        j = i-1;
        while (j > 0 and a[j] <= a[i]) j--;
        p[i] = j;
    }
    return p
}
```

---

$$T(n) = \sum_{i=1}^n \sum_{j=0}^{i-1} 1 = 1 + 2 + \dots + (n-2) + (n-1) = \sum_{i=1}^{n-1} i.$$

$$T(n) = \frac{(n-1)n}{2}.$$

# Recurrences

Arise naturally in analysis of divide-and-conquer algorithms

- **Divide**: Divide the problem into two or more sub-problems (ideally of roughly equal sizes)
- **Conquer**: Solve each sub-problem recursively
- **Combine**: Combine the solutions to the sub-problems into a single global solution.

# Recurrences

- To analyze recursive procedures such as divide-and-conquer, we need to set up a recurrence.
- Example: Suppose we break a problem into two sub-problems, each of size roughly  $n/2$ .
- Additional overhead of splitting and merging the solutions is  $O(n)$ .
- When sub-problems are reduced to size 1, we can solve them in  $O(1)$  time.
- Ignoring constants and writing  $O(n)$  as  $n$ , we get:

$$\begin{aligned}T(n) &= 1 \text{ if } n = 1, \\T(n) &= 2T(n/2) + n \text{ if } n > 1\end{aligned}$$

# Example Problem

- Use mathematical induction to show that when  $n$  is an exact power of 2, the solution of the recurrence

$$T(n) = \begin{cases} 2, & \text{if } n = 2, \\ 2T\left(\frac{n}{2}\right) + n, & \text{if } n = 2^k, \text{ for } k > 1 \end{cases}$$

is  $T(n) = n \lg n$

# Next Time

- Other Asymptotic Forms
- Read Section 2.2