#### **Adversarial Search**

## Toolbox so far

- Uninformed search
   BFS, DFS, uniform cost search
- Heuristic search

 $-A^*$ 

**Common environmental factors**: static, discrete, fully observable, deterministic actions. Also: single agent, non-episodic.

# Kick it up a notch!

• Add a second agent, but not controlled by us.



- Assume this agent is our adversary.
- Environment (for now)
  - Still static
  - Still discrete
  - Still fully observable (for now)
  - Still deterministic (for now)

#### Games!

• Deterministic, turn-taking, two-player, zerosum games of perfect information.





#### **Checkers Is Solved**

Jonathan Schaeffer,\* Neil Burch, Yngvi Björnsson,† Akihiro Kishimoto,‡ Martin Müller, Robert Lake, Paul Lu, Steve Sutphen

The game of checkers has roughly 500 billion billion possible positions (5  $\times$  10<sup>20</sup>). The task of solving the game, determining the final result in a game with no mistakes made by either player, is daunting. Since 1989, almost continuously, dozens of computers have been working on solving

best known is the four-color theorem (9). This deceptively simple conjecture-that given an arbitrary map with countries, you need at most four different colors to guarantee that no two adjoining countries have the same color-has been extremely difficult to prove analytically. In 1976, a computational proof was demonstrated. Despite the convincing result, some mathematicians were skeptical, distrusting proofs that had not been verified using human-derived theorems. Although important components of the checkers

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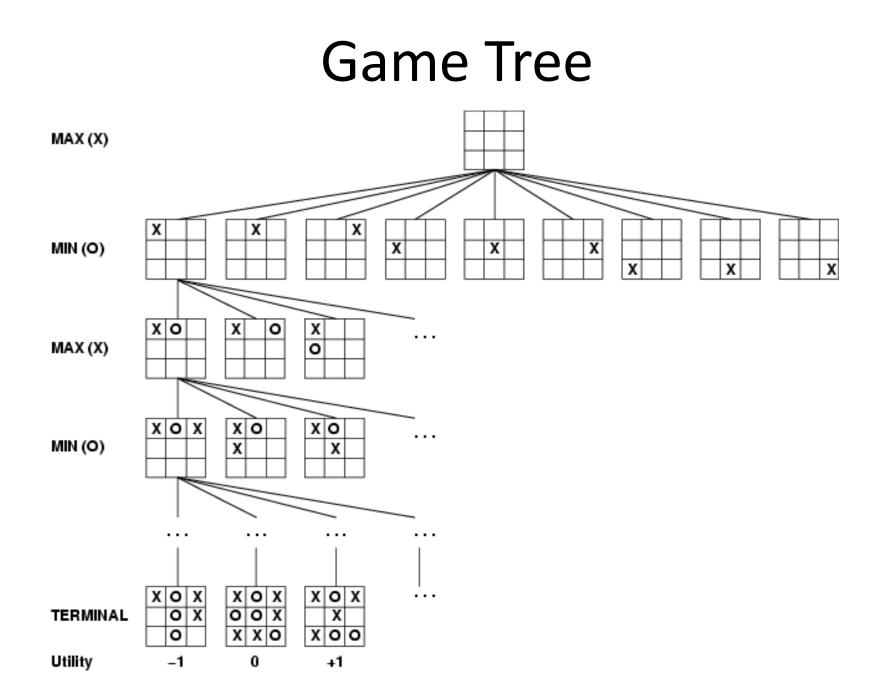
### Adversarial search

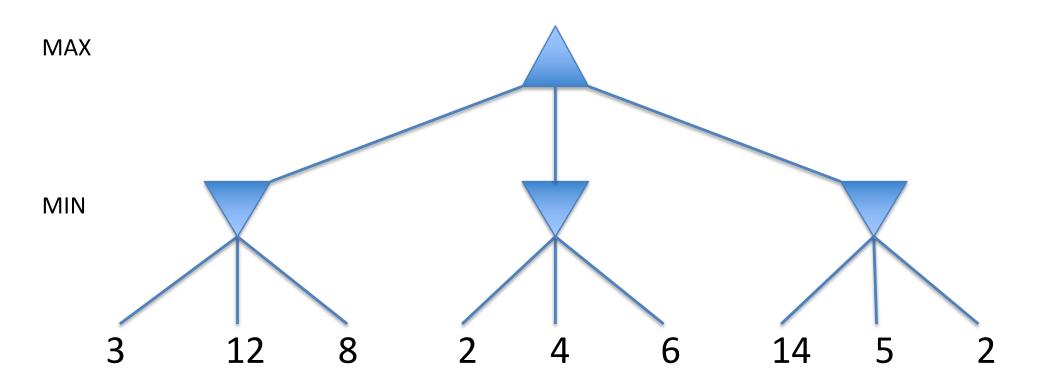
• Still search!

- But another agent will alternate actions with us.

- Main new concept:
  - Two players are called MAX and MIN.
  - Only works for zero-sum games.
    - Strictly competitive (no cooperation).
    - What is good for me is equally bad for my opponent (in regards to winning and losing).
  - Most "normal" 2-player games are zero-sum.

- Most all of our concepts from state-space search transfer here.
- Initial state
- PLAYER(s): Defines who makes the next move at a state.
- ACTIONS(s): Returns the set of legal moves in a state.
- RESULT(s, a): Returns what state you go into (transition model)
- TERMINAL-TEST(s): Returns true if s is a terminal state.
- UTILITY(s, p): Numeric value of a terminal state s for player p.





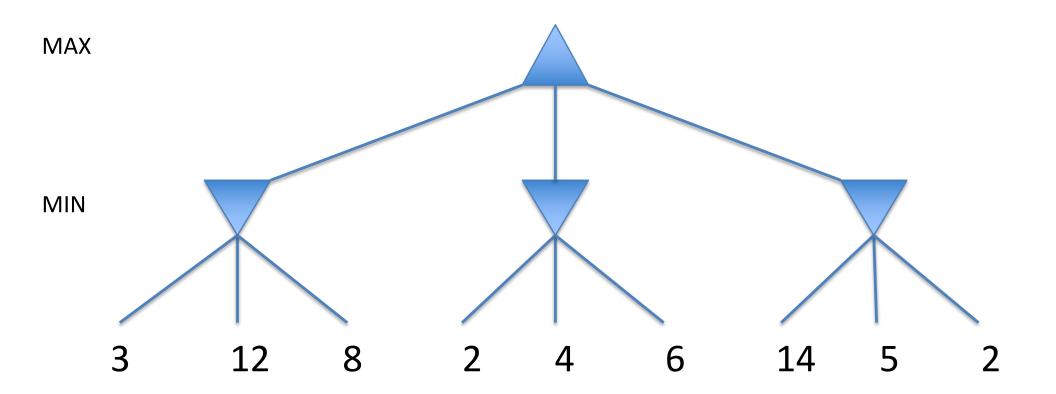
## Minimax algorithm

- Select the best move for you, assuming your opponent is selecting the best move for themselves.
- Works like DFS.

### Minimax algorithm

minimax(s) =utility(s)if s is terminalmax\_a in actions(s)minimax(result(s, a))min\_a in actions(s)minimax(result(s, a))if player(s)=MIN

result(s, a) means the new state generated by taking action *a* in state *s*.



## minimax(s) =

utility(s)

max<sub>a in actions(s)</sub> minimax(result(s, a))
min<sub>a in actions(s)</sub> minimax(result(s, a))

if s is terminal
if player(s)=MAX
if player(s)=MIN

## **Properties of minimax**

- Complete?
  - Yes (assuming tree is finite)
- Optimal?
  - Yes (assuming opponent is also optimal)
- Time complexity: O(b<sup>m</sup>)
- Space complexity: O(bm) (like DFS)
- But for chess, b ≈ 35, m ≈ 100, so this time is completely infeasible!

#### Real-World Minimax

- The minimax algorithm given here only stores the utility values; "real-world" minimax should store utility values and also the move that gives you the value.
- This is usually done by keeping an auxiliary data structure called a transposition table; this table also cuts down on search time.
  - Table stores, for every state, the minimax value and corresponding best move.

## Nim

- How to represent a state?
- How to represent an action?